

Task 2.2.3

Numerical Flowfield Computation by Simplified Methods

Adaptation of 3D Vortex Filament Methods

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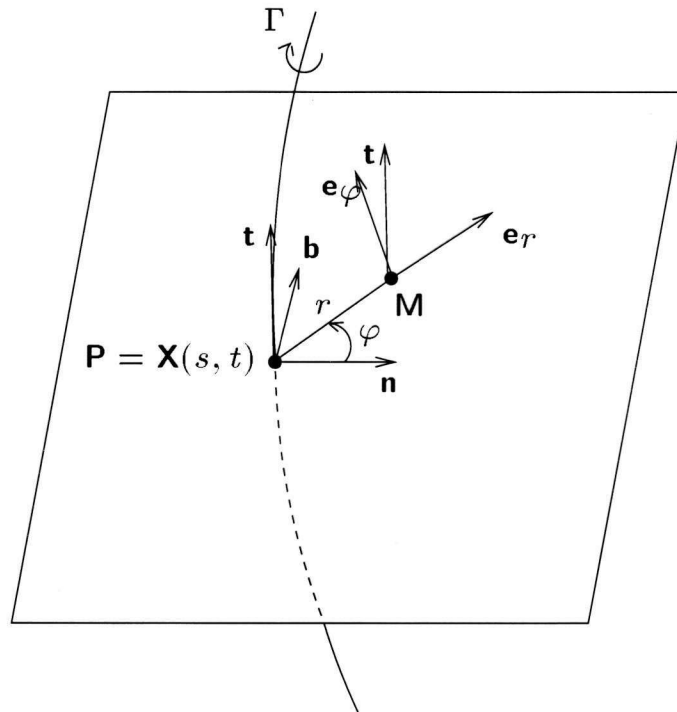
<http://www.maths.warwick.ac.uk/~dmargeri>



IMFT
INSTITUT DE MECANIQUE
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Equation of motion of slender filaments



The centerline and the local co-ordinates of the vortex filament.

Slenderness \implies **MAE** in the Navier Stokes Equations
 \implies Separated Slender Filaments (No reconnection)
 \implies No short-wavelength

\implies Callegari and Ting: Siam Applied Math. 78

\implies Klein and Knio : J. Fluid Mech. 95

\implies Klein and Knio : J. Comput. 2000

1) The equation of Callegari and Ting

$$\partial \mathbf{X} / \partial t = \mathbf{A} + \frac{\Gamma K(s, t)}{4\pi} B \mathbf{b}(s, t),$$

where

$$\mathbf{A}(s, t) = \frac{\Gamma}{4\pi} \int_{-\pi}^{+\pi} \sigma(s + s', t) \mathbf{N} ds',$$

$$\mathbf{N} = \frac{\mathbf{t}(s + s', t) \times (\mathbf{X}(s, t) - \mathbf{X}(s + s', t))}{|\mathbf{X}(s, t) - \mathbf{X}(s + s', t)|^3} - \frac{K(s, t) \mathbf{b}(s, t)}{2 |\lambda(s, s', t)|},$$

$$\sigma(s, t) = |\partial \mathbf{X} / \partial s|,$$

$$\lambda(s, s', t) = \int_s^{s+s'} \sigma(s^*, t) ds^*,$$

and

$$B = -\log \epsilon + \log(S) - 1 + C_v(t) + C_w(t)$$

K : local curvature

S : length of the filament

ϵ : small dimensionless thickness

Similar vortex core

$$\begin{aligned} C_v(t) &= [1 + \gamma - \ln 2]/2 - \ln(\bar{\delta}), \\ C_w(t) &= -2(S_0/S)^4(m_0/(\Gamma\bar{\delta}))^2, \end{aligned}$$

where

$$\begin{aligned} \bar{\delta}^2(t) &= \bar{\delta}_0^2 \left(\frac{S_0}{S(t)} \right) \left(1 + \frac{\bar{\delta}_v^2}{\bar{\delta}_0^2} \right) \\ \bar{\delta}_v^2 &= 4\bar{\nu} \int_0^t \frac{S(t')}{S_0} dt', \end{aligned}$$

γ = Euler number. Subscript 0 stands for initial.

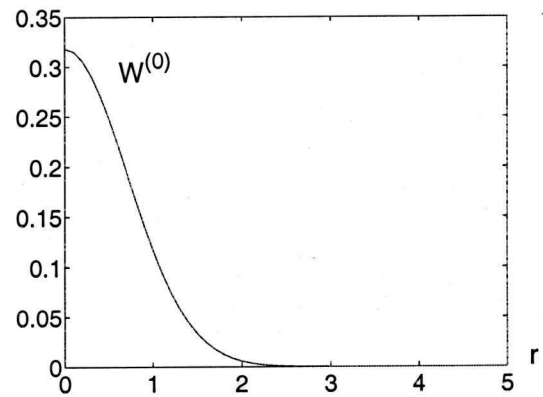
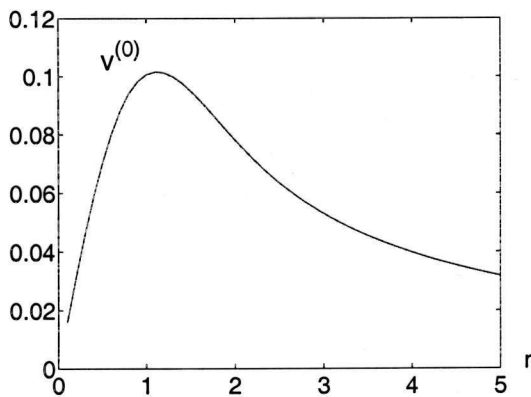
$\bar{\delta} = \delta/\epsilon$: the stretched radius

$\bar{\nu} = \nu/\epsilon^2$ is the stretched kinematic viscosity.

m_0 : the initial axial flux of the ring.

Circumferential $v^{(0)}$ and axial $w^{(0)}$ velocities:

$$v^{(0)} = \frac{\Gamma}{2\pi\bar{r}} \left[1 - e^{-(\bar{r}/\bar{\delta})^2} \right], \quad w^{(0)} = \frac{m_0}{\pi\bar{\delta}^2} \left(\frac{S_0}{S} \right)^2 e^{-(\bar{r}/\bar{\delta})^2},$$



$\bar{r} = r/\epsilon$: the stretched radial distance to the filament,

2) M1 method of Knio and Klein

$$\partial \mathbf{X} / \partial t = \mathbf{v}_{\sigma_1} + (\mathbf{v}_{\sigma_1} - \mathbf{v}_{\sigma_2}) \frac{\log(\sigma_1 / \delta^{ttm})}{\log(\sigma_2 / \sigma_1)}$$

where

$$\mathbf{v}_x = \frac{\Gamma}{4\pi} \int_C \sigma(s', t) \mathbf{N}_x ds',$$

$$\mathbf{N}_x = \frac{\mathbf{t}(s', t) \times (\mathbf{X}(s, t) - \mathbf{X}(s', t))}{\left[|\mathbf{X}(s, t) - \mathbf{X}(s', t)|^2 \right]^{3/2}} \kappa \left(\frac{|\mathbf{X}(s, t) - \mathbf{X}(s', t)|}{x} \right)$$

$$\kappa(r) = \tanh(r^3)$$

and

$$\sigma_1 = 3\sigma_{max},$$

$$\sigma_2 = 2\sigma_{max},$$

$$\sigma_{max} = ds \max_{s \in [0, 2\pi]} \sigma(s, t).$$

$$\delta^{ttm} = \epsilon \exp(C^{ttm} + 1 - C_v(t) - C_w(t)),$$

With the choice of $\kappa(r) = \tanh(r^3)$, the C^{ttm} constant is $C^{ttm} = -0.4202$.

EZ-vortex¹: a Slender Vortex Filament solver (SVF)

1) Input: Initial position of the filaments

2) Solver: SVF solver for *closed* or *open* filaments

- Equation:

- The Callegari and Ting Equation (Implicit stepping)
- The M1 method of Knio and Klein (Adams-Bashforth or Implicit)

- Spatial derivatives: Finit. Diff. or Spectral

- Core: similar core or non-similar (Laguerre series)

- Inviscid or viscous

3) Output:

- Run-time drawing with OpenGL (SGI or linux)

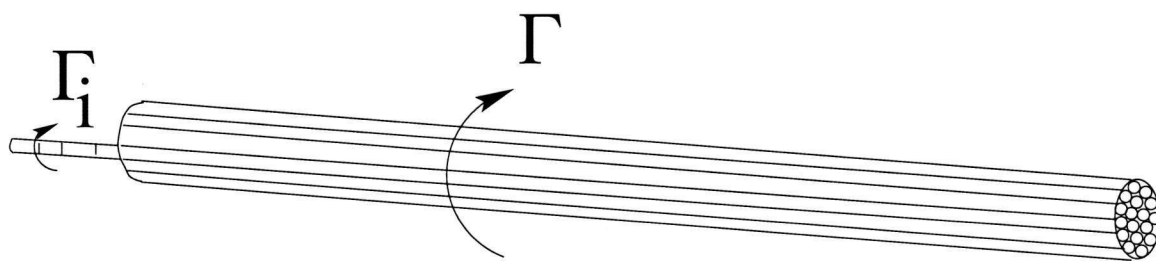
- File *history.dat* and mode 'Visualisation' of this file

- Movie of the simulation

¹ D.Margerit, A.Giovannini, P. Brancher: EZ-vortex documentation: a Slender Vortex Filament solver

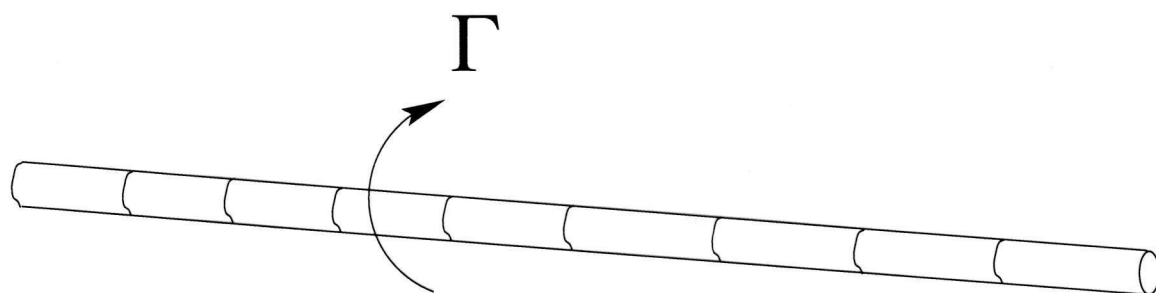
3D Numerical Vortex Methods

1) Vortex Blob or Vortex filament Methods



- + No numerical diffusion. Vorticity domain \ll Flow dom.
- + Great Nbr filaments (or blobs) / section to converge
- + Stiff when the thickness is small (boundary layer)
- + Viscous diffusion computed by:
a *random walk* or a *deterministic technique*
- + N-body problem \implies Fast solvers

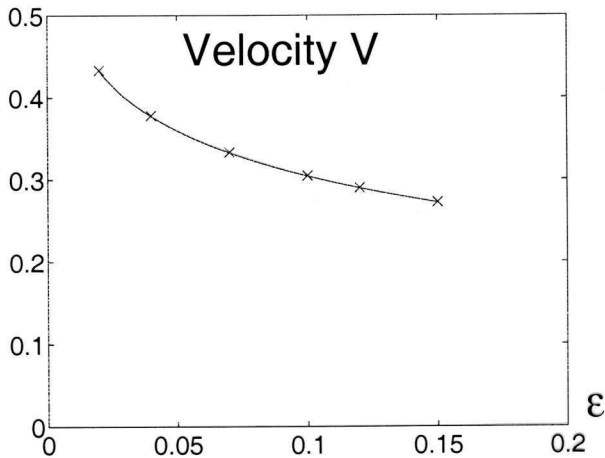
2) Slender Vortex filament solver:



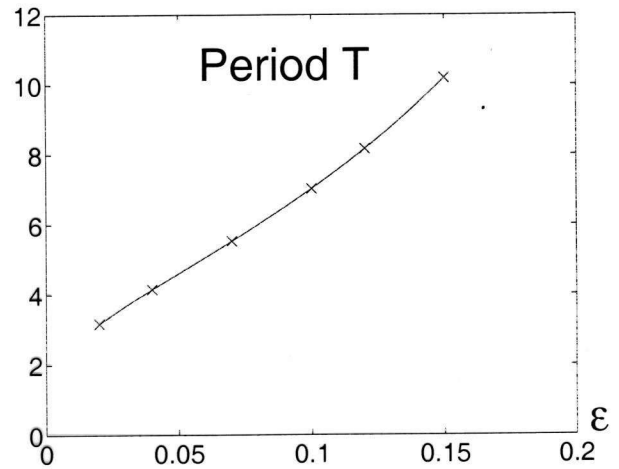
- + Nbr filaments (or blobs) / section = 1
- + Not stiff with thickness:
boundary layer solved theoretically
- + Viscous diffusion solved theoretically
 \implies Fast and accurate
but
 \implies Small thickness, no reconnection, no short wavelengths

Validation

Linear stability analysis of a perturbed circular vortex ring (similar vortex and inviscid):

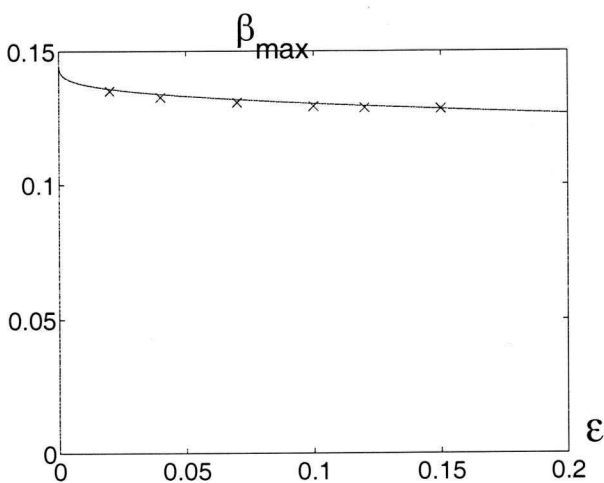


Velocity $V = f(\epsilon)$

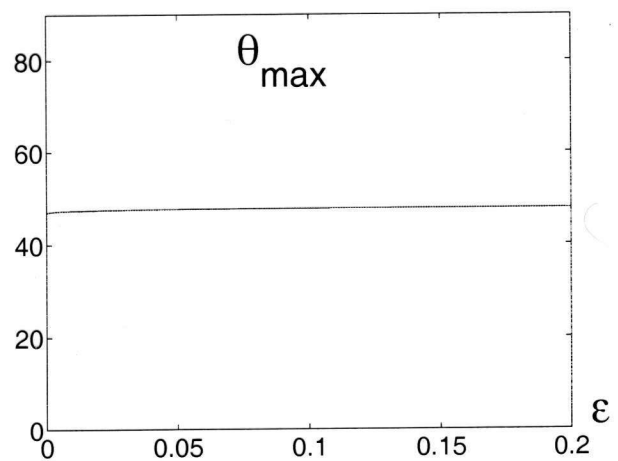


Period $T = f(\epsilon)$ for mode 3

Linear stability analysis of a pair of contra-rotating vortex filaments (similar vortex and inviscid):



Ampl. rate $\beta_{max} = f(\epsilon)$



Planar angle $\theta_{max} = f(\epsilon)$

Movies

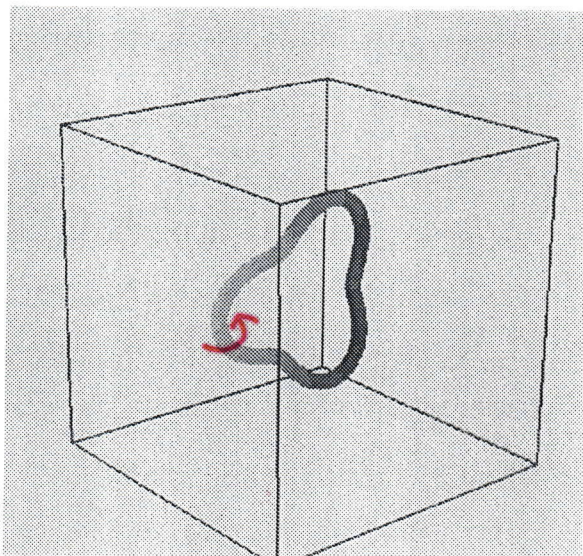


Figure 1:

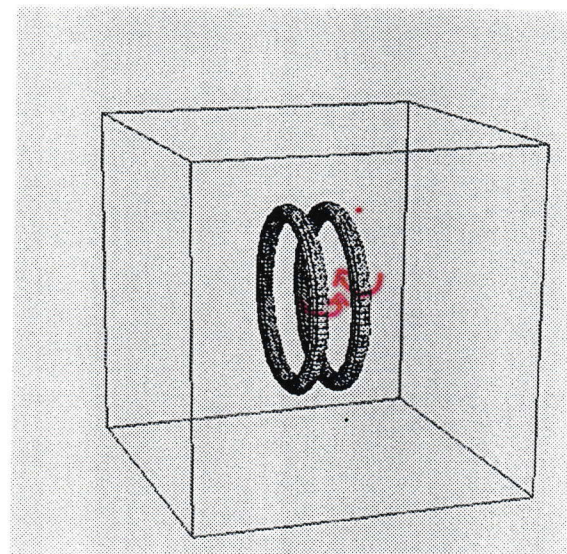


Figure 2:

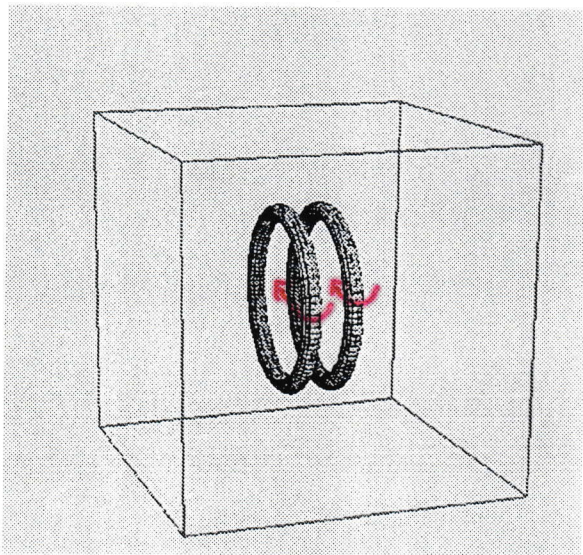
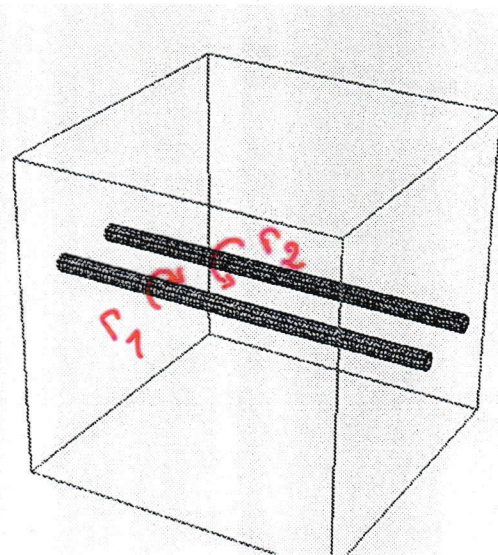


Figure 3:



<http://www.maths.warwick.ac.uk/~dmargeri/moviei.html>