THE COMPLETE FIRST ORDER EXPANSION OF A SLENDER VORTEX RING

 $\begin{array}{c} {\rm D.~Margerit} \\ {\it LEMTA,CNRS~URA~875,Nancy,France} \end{array}$

Abstract. Equations for the axisymmetric part of the velocity field and for the equation of motion of a *non circular* slender vortex ring are given at first order. This is the correction to the known leading order given by Callegari and Ting [2].

I. DEFINITIONS AND NOTATIONS

The length scales of the vortex ring that are different from its thickness δ , for example: the radius of curvature, the ring length, are of the same order L with $\delta/L = O(\epsilon) << 1$. The central curve is described parametrically with the use of a function $\mathbf{X} = \mathbf{X}(s,t)$. A local curvilinear co-ordinate system (r,φ,s) , with a frame $(\mathbf{e}_r,\mathbf{e}_\theta,\mathbf{t})$, is introduced near this central curve [2]. There is an *outer problem* defined by the *outer limit*: $\epsilon \to 0$ with r fixed, which describes the situation far from the central line and an *inner problem* defined by the *inner limit*: $\epsilon \to 0$ with $\overline{r} = r/\epsilon$ fixed, which describes the situation near the central line.

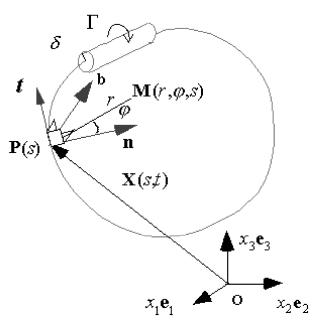


FIG. 1. The central curve and the local co-ordinates of the vortex ring.

The change between Cartesian co-ordinates $\mathbf{M}(x_1,x_2,x_3)$ and local co-ordinates $\mathbf{M}(r,\varphi,s)$ satisfies:

$$\mathbf{x} = \mathbf{OM} = \mathbf{X}(s,t) + r\mathbf{e}_r(\varphi, s, t)$$

The variable

$$\sigma(s,t) = |\mathbf{X}_s| \tag{1}$$

is introduced, where | | is the usual norm of \mathbb{R}^3 . The Frenet formulas are

$$\mathbf{X}_{s} = \sigma \mathbf{t} \qquad \mathbf{t}_{s} = \sigma K \mathbf{n} \mathbf{n}_{s} = \sigma (T \mathbf{b} - K \mathbf{t}) \qquad \mathbf{b}_{s} = -\sigma T \mathbf{n}$$

$$(2)$$

where T the local torsion of \mathcal{C} and K the local curvature of \mathcal{C} . Notice that here and throughout this paper, the differentiation $\partial f/\partial x$ of a function f with respect to its variable x is denoted f_x ; \times is the cross-product and \cdot is the dot-product. The polar vectors $(\mathbf{e}_r, \mathbf{e}_\theta)$ are

$$\mathbf{e}_r(\varphi, s) = +\mathbf{n}(s)\cos(\varphi) + \mathbf{b}(s)\sin(\varphi) \tag{3}$$

$$\mathbf{e}_{\theta}(\varphi, s) = -\mathbf{n}(s)\sin(\varphi) + \mathbf{b}(s)\cos(\varphi) \tag{4}$$

The small parameter ϵ is defined by $\epsilon = \delta_0/L = \delta(t=0)/L$.

 ${\bf Dimensionless\ variables:}$

$$\mathbf{X}^* = \mathbf{X}/L \qquad S^* = S/L$$

$$K^* = LK \qquad T^* = LT$$

$$\delta^* = \delta/L \qquad t^* = t/(L^2/\Gamma)$$

$$\mathbf{v}^* = \mathbf{v}/(\Gamma/L) \qquad \omega^* = \omega/(\Gamma/L^2)$$

$$r^* = r/L \qquad \sigma^* = \sigma/L$$

are introduced, where S is the length of the ring and Γ is its circulation. Here, \mathbf{v} and $\boldsymbol{\omega}$ are respectively the velocity and the vorticity fields. From here on, all quantities are dimensionless and the asterisks are omitted. The Reynolds number R_e is defined by $R_e = \Gamma/\nu$ where ν is the kinematic viscosity of the fluid. Let us define the number α such that $R_e^{-1/2} = \alpha \epsilon$. Both inviscid: $\alpha = 0$ and viscous: $\alpha = O(1)$ vortex rings are studied. The velocity is decomposed as follows:

$$\mathbf{v}(r,\varphi,s,t,\epsilon) = \dot{\mathbf{X}}(s,t,\epsilon) + \mathbf{V}(r,\varphi,s,t,\epsilon) \tag{5}$$

where

$$\mathbf{V} = u\mathbf{e}_r + v\mathbf{e}_\theta + w\mathbf{t} \tag{6}$$

and

$$\dot{\mathbf{X}} = \frac{\partial \mathbf{X}}{\partial t} \tag{7}$$

The following forms are chosen for the inner expansions of the velocity field:

$$\begin{array}{lll} u^{inn} & = & u^{(1)}(\overline{r},\varphi,s,t) & + \dots \\ v^{inn} & = \epsilon^{-1}v^{(0)}(\overline{r},s,t) & + v^{(1)}(\overline{r},\varphi,s,t) & + \dots \\ w^{inn} & = \epsilon^{-1}w^{(0)}(\overline{r},s,t) & + w^{(1)}(\overline{r},\varphi,s,t) & + \dots \end{array} \tag{8}$$

with an expression of the central curve of the form :

$$\mathbf{X} = \mathbf{X}^{(0)}(s,t) + \epsilon \mathbf{X}^{(1)}(s,t) + \dots$$
(9)

II. LIMIT OF \mathbf{v}^{inn} AT $\overline{r} \to \infty$ UP TO ORDER ϵ THROUGH BIOT AND SAVART LAW

Let us have a vorticity field of the form:

$$\omega = \frac{1}{\epsilon^2} \omega^{(0)}(\overline{r}, \varphi, s) \tag{10}$$

The Biot and Savart law is given on local co-ordinates by the formula:

$$\mathbf{v}(r,\varphi,s,t,\epsilon) \tag{11}$$

$$= \frac{1}{4\pi} \iiint \frac{\epsilon^2 \boldsymbol{\omega}(\overline{r}', \boldsymbol{\varphi}', s', t, \epsilon) \times [(\mathbf{X}(s, t, \epsilon) + r\mathbf{e}_r(\boldsymbol{\varphi}, s, t, \epsilon)) - (\mathbf{X}(s', t, \epsilon) + \epsilon \overline{r}' \mathbf{e}_r')]}{|(\mathbf{X}(s, t, \epsilon) + r\mathbf{e}_r(\boldsymbol{\varphi}, s, t, \epsilon)) - (\mathbf{X}(s', t, \epsilon) + \epsilon \overline{r}' \mathbf{e}_r')|} h_3' \overline{r}' d\overline{r}' d\boldsymbol{\varphi}' ds'$$
(12)

where

$$h_3' = \sigma(s', t)(1 - K(s', t)\epsilon \overline{r}' \cos(\varphi')). \tag{13}$$

Next, in this section, s will be an arc length parameter.

The outer expansion of velocity is:

$$\mathbf{v}^{out}(r,\varphi,s,\epsilon) = \mathbf{v}^{out^{(0)}}(r,\varphi,s) + \epsilon \mathbf{v}^{out^{(1)}}(r,\varphi,s) + O(\epsilon^2).$$

If

$$\iint (\boldsymbol{\omega} - [\boldsymbol{\omega} \cdot \mathbf{t}] \mathbf{t}) \, \overline{r} d\overline{r} d\varphi = 0 \tag{14}$$

one obtains:

$$\mathbf{v}^{out(0)}(r,\varphi,s,\epsilon) = \frac{1}{4\pi} \int_{\mathcal{C}} \frac{\mathbf{t}(s') \times (\mathbf{x} - \mathbf{X}(s'))}{\left| (\mathbf{x} - \mathbf{X}(s')) \right|^3} ds'$$
(15)

$$\mathbf{v}^{out(1)}(r,\varphi,s)$$

$$= \frac{1}{4\pi} \iiint \frac{\boldsymbol{\omega}'^{(0)} \times (\mathbf{x} - \mathbf{X}')}{|\mathbf{x} - \mathbf{X}'|^3} \overline{r}'^2 K(s') \cos(\varphi') d\overline{r}' d\varphi' ds'$$

$$- \frac{1}{4\pi} \iiint 3 \frac{[\boldsymbol{\omega}'^{(0)} \times (\mathbf{x} - \mathbf{X}')] [\mathbf{e}'_r \cdot (\mathbf{x} - \mathbf{X}')]}{|\mathbf{x} - \mathbf{X}'|^5} \overline{r}'^2 d\overline{r}' d\varphi' ds'$$

$$- \frac{1}{4\pi} \iiint \frac{\mathbf{e}'_r \times \boldsymbol{\omega}'^{(0)}}{|\mathbf{x} - \mathbf{X}'|^3} \overline{r}'^2 d\overline{r}' d\varphi' ds'$$
(16)

with:

$$\mathbf{x} = \mathbf{X}(s,t) + r\mathbf{e}_r(\varphi, s, t) \tag{17}$$

Thus at leading order in outer co-ordinates, the velocity field exactly correspond to the Dirac delta distribution

 $\delta_{\mathcal{C}}\mathbf{t}$ on the central line.

In case

$$\boldsymbol{\omega}^{(0)} = \omega_2(\overline{r})\mathbf{e}_{\theta} + \omega_3(\overline{r})\mathbf{t},\tag{18}$$

when $r = \epsilon \overline{r}$ is put in $\mathbf{v}^{out}(r \to 0, \varphi, s)$, one obtains :

$$\mathbf{v}^{inn}(\overline{r} \to \infty, \varphi, s) = \frac{1}{\epsilon} \mathbf{v}^{inn(0)}(\overline{r} \to \infty, \varphi, s) + \ln \epsilon \mathbf{v}^{inn(01)}(\overline{r} \to \infty, \varphi, s) + \mathbf{v}^{inn(1)}(\overline{r} \to \infty, \varphi, s)$$
$$+\epsilon \ln \epsilon \mathbf{v}^{inn(12)}(\overline{r} \to \infty, \varphi, s) + \epsilon \mathbf{v}^{inn(2)}(\overline{r} \to \infty, \varphi, s) + O(\epsilon^2 \ln \epsilon) \tag{19}$$

with:

$$\mathbf{v}^{inn(0)}(\overline{r} \to \infty, \varphi, s) = \frac{1}{2\pi} \frac{\mathbf{e}_{\theta}}{\overline{r}} + \frac{\mathbf{I}_{1}}{\overline{r}^{2}} + O(\frac{1}{\overline{r}^{3}})$$
(20)

$$\mathbf{v}^{inn(01)}(\overline{r} \to \infty, \varphi, s) = -\frac{K}{4\pi}\mathbf{b}$$
(21)

$$\mathbf{v}^{inn(1)}(\overline{r} \to \infty, \varphi, s) = \frac{K}{4\pi} \left[\ln \frac{S}{\overline{r}} - 1 \right] \mathbf{b} + \frac{K}{4\pi} \cos \varphi \mathbf{e}_{\theta} + \mathbf{A} + \frac{\mathbf{I}_2}{\overline{r}} + O(\frac{1}{\overline{r}^2})$$
 (22)

$$\mathbf{v}^{inn(12)}(\overline{r} \to \infty, \varphi, s) = \mathbf{I}_3 + \mathbf{I}_5 \overline{r} \tag{23}$$

$$\mathbf{v}^{inn(2)}(\overline{r} \to \infty, \varphi, s) = (\mathbf{I}_3 + \mathbf{I}_5 \overline{r}) \ln \overline{r} + (\mathbf{I}_6 + \mathbf{E}_2(\varphi, s)) \overline{r} + \mathbf{I}_4 + \mathbf{E}_1(s)$$
(24)

$$\mathbf{E}_{2}(\varphi, s) = \frac{1}{4\pi} \left(\mathbf{B}(\varphi, s) - 3\mathbf{C}(\varphi, s) \right) \tag{25}$$

where expressions of **A**, **B**, **C**, \mathbf{E}_i , \mathbf{I}_i (i=1...6) are given in Appendix.

This expression (11) can be compared with that of Fukumoto and Miyazaki [4] (page 373) and Callegari et Ting [2] (page 173). It is the same all but here $\bf A$, $\bf B$, $\bf C$ and order ϵ are given. Besides here the derivation was performed in an algorithmic way with formal calculus (Maple) and with the matched asymptotic expansion of singular integral method following François [3] or Bender and Orszag [1].

Let us notice that the same result would have be obtained if $\overline{r} \to \infty$ were put in the inner expansion of Biot and Savart law [6].

This result will be used in the following when the asymptotic matching will be performed.

III. RESULTS AT ORDER 0

Callegari and Ting [2] considered the case where $v^{(0)}, w^{(0)}$ are independent of s so that some compatibility conditions are satisfied. They deduced the following equations for $v^{(0)}, w^{(0)}$ from Navier Stokes second order equations:

$$\overline{r}\frac{\partial v^{(0)}(\overline{r},t)}{\partial t} - \alpha^2 \frac{\partial v^{(0)}(\overline{r},t)}{\partial \overline{r}} + \frac{\alpha^2}{\overline{r}}v^{(0)}(\overline{r},t) - \alpha^2 \overline{r}\frac{\partial^2 v^{(0)}(\overline{r},t)}{\partial \overline{r}^2} - \frac{1}{2}\overline{r}\frac{\partial \overline{r}v^{(0)}(\overline{r},t)}{\partial \overline{r}}\frac{\dot{S}^{(0)}}{S^{(0)}} = 0$$
(26)

$$\overline{r}\frac{\partial w^{(0)}(\overline{r},t)}{\partial t} - \alpha^2 \frac{\partial w^{(0)}(\overline{r},t)}{\partial \overline{r}} - \alpha^2 \overline{r}\frac{\partial^2 w^{(0)}(\overline{r},t)}{\partial \overline{r}^2} - \frac{1}{2}\overline{r}^4 (\frac{w^{(0)}(\overline{r},t)}{\overline{r}^2})_{\overline{r}}\frac{\dot{S}^{(0)}}{S^{(0)}} = 0$$
 (27)

where $S^{(0)}$ is the length of the ring.

Through matching, they found the following equation for $\mathbf{X}^{(0)}(s,t)$:

$$\dot{\mathbf{X}}^{(0)} - (\dot{\mathbf{X}}^{(0)} \cdot \mathbf{t})\mathbf{t} = \left(\frac{K^{(0)}}{4\pi} \left[\ln \frac{S^{(0)}}{\epsilon} - 1 \right] + K^{(0)}C^*\right)\mathbf{b} + \mathbf{A} - (\mathbf{A} \cdot \mathbf{t})\mathbf{t}$$
(28)

where

$$C^{*}(t) = \frac{1}{4\pi} \left\{ +\frac{1}{2} + \lim_{\overline{r} \to \infty} \overline{r} \left(4\pi^{2} \int_{0}^{\overline{r}} \xi \left(v^{(0)} \right)^{2} d\xi - \ln(\overline{r}) \right) - 8\pi^{2} \int_{0}^{\infty} \xi(w^{(0)})^{2} d\xi \right\}$$
(29)

$$\lambda(s,\overline{s},t) = \int_{s}^{s+\overline{s}} \sigma^{(0)}(s^*,t)ds^*$$
(30)

$$\mathbf{A}(s,t) \tag{31}$$

$$= \frac{1}{4\pi} \int_{-\pi}^{+\pi} \left[-\sigma^{(0)}(s+\overline{s},t) \frac{\mathbf{t}^{(0)}(s+\overline{s},t) \times (\mathbf{X}^{(0)}(s+\overline{s},t) - \mathbf{X}^{(0)}(s,t))}{\left|\mathbf{X}^{(0)}(s+\overline{s},t) - \mathbf{X}^{(0)}(s,t)\right|^{3}} - \frac{K^{(0)}(s,t)}{2} \frac{\mathbf{b}^{(0)}(s,t)\sigma^{(0)}(s+\overline{s},t)}{\left|\lambda^{(0)}(s,\overline{s},t)\right|} \right] d\overline{s}$$
(32)

IV. RESULTS AT ORDER 1

In the same way that first order Navier Stokes equations give compatibility equations for $v^{(0)}, w^{(0)}$, second order Navier Stokes equations give compatibility equations for the axisymmetric part $v_c^{(1)}, w_c^{(1)}$ of $v^{(1)}, w^{(1)}$. These equations are automatically satisfied if $v_c^{(1)}$ is assumed to be independent of s and if $w_c^{(1)}$ is such that:

$$\frac{\partial w_c^{(1)}(\overline{r}, s, t)}{\partial c} = -\dot{\sigma}^{(0)} + a(s, t)\sigma^{(0)}$$
(33)

$$a(s,t) = \dot{S}^{(0)}/S^{(0)} \tag{34}$$

We write:

$$w_c^{(1)}(\overline{r}, s, t) = w_{cc}^{(1)}(s, t) + w_c^{(1)}(\overline{r}, t)$$
(35)

Equations for $v_c^{(1)}, w_c^{(1)}$ can be extracted from third order Navier Stokes equations. We did this with the use of symbolic calculus (on maple) in the following way: we obtained third order Navier Stokes equations, then we carried out the φ -average and s-average of the axial and circumferential components of the third order momentum equations using the third order continuity equation to eliminate $u_c^{(2)}$. Lots of terms vanished and we found equations for $v_c^{(1)}, w_c^{(1)}$. Note that Fukumoto and Miyazaki ([4] page 378) postulated $v_c^{(1)} = 0$, kept $w_c^{(1)}$ dependent of s, and did not have equation for $w_c^{(1)}$. The following equations are obtained:

$$S^{(0)} \left(\frac{\partial v_c^{(1)}}{\partial t} - \alpha^2 \left[\frac{1}{\overline{r}} (\overline{r} v_c^{(1)})_{\overline{r}} \right]_{\overline{r}} \right) - \frac{1}{2} \dot{S}^{(0)} \left(\overline{r} v_c^{(1)} \right)_{\overline{r}} = \frac{\overline{r}}{2} \left(\dot{S}^{(1)} - S^{(1)} \frac{\dot{S}^{(0)}}{S^{(0)}} \right) \zeta^{(0)}$$

$$(36)$$

where

$$S^{(1)} = \int_{0}^{2\pi} \sigma^{(1)} ds. \tag{37}$$

$$S^{(0)} \left(\frac{\partial w_c^{(1)}}{\partial t} - \alpha^2 \left[\frac{1}{\bar{r}} \left(\bar{r} \left(w_c^{(1)} \right)_{\bar{r}} \right)_{\bar{r}} \right]_{\bar{r}} \right) - \frac{1}{2} \dot{S}^{(0)} \bar{r}^3 \left(\frac{w_c^{(1)}}{\bar{r}^2} \right)_{\bar{r}} = \frac{\bar{r}^3}{2} (w^{(0)} / \bar{r}^2)_{\bar{r}} \left(\dot{S}^{(1)} - S^{(1)} \frac{\dot{S}^{(0)}}{S^{(0)}} \right) + \frac{1}{4\pi} \left(\ln(\frac{S}{\epsilon}) + C - 4\pi \bar{r} v^{(0)} \right) \int_0^{2\pi} K^{(0)} \mathbf{A}_s(s, t) \cdot \mathbf{b}^{(0)} ds$$

$$- \int_0^{2\pi} \sigma^{(0)} \mathbf{A}(s, t) \cdot \mathbf{t}^{(0)} ds - \int_0^{2\pi} \sigma^{(0)} \frac{\partial w_{cc}^{(1)}(s, t)}{\partial t} ds - \frac{\dot{S}^{(0)}}{S^{(0)}} \int_0^{2\pi} \sigma^{(0)} w_{cc}^{(1)}(s, t) ds$$

$$(38)$$

The left hand side of these equations are the same for $v_c^{(1)}(\overline{r},t)$ and $w_c^{(1)}(\overline{r},t)$ than for $v^{(0)}(\overline{r},t)$ and $w^{(0)}(\overline{r},t)$. We may notice that even if initially $w_c^{(1)}(\overline{r},0)=0$, the right hand side terms will induce $w_c^{(1)}(\overline{r},0)\neq 0$ when $t\neq 0$.

These equations for $v_c^{(1)}$, $w_c^{(1)}$ are linked to $\mathbf{X}^{(1)}(s,t)$, so an equation for $\mathbf{X}^{(1)}$ is needed to have a closed system of equations for the first order solutions $v_c^{(1)}$, $w_c^{(1)}$ and $\mathbf{X}^{(1)}$. The best attempt to find this equation is by Fukumoto and Miyazaki ([4] page 382), where contribution from Navier Stokes equations up to order ϵ^1 have been found in order to performed the asymptotic matching. We may note that in their expression the term due to first order curvature $K^{(1)}$ is missing. Moreover, their expression for $\mathbf{X}^{(1)}$ is not complete, as local and non-local (named \mathbf{Q} in [4]) contribution from Biot and Savart integral are given only up to order ϵ^0 in Fukumoto and Miyazaki [4] (page 373) and Callegari and Ting [2] (page 173), while order ϵ^1 is obviously needed to obtain complete and correct equation for $\mathbf{X}^{(1)}$. The complete expression, up to ϵ order, was performed in section 2. The matching is then done and lacking terms in equation of $\mathbf{X}^{(1)}$ are found:

$$\dot{\mathbf{X}}^{(1)} - (\dot{\mathbf{X}}^{(1)} \cdot \mathbf{t})\mathbf{t} = \left\{ C_2^* - \frac{1}{8\pi} K^{(1)}(s,t) + \frac{1}{4\pi} K^{(1)}(s,t) \ln \epsilon - \frac{m}{4\pi} K_s \left[3 \ln \epsilon + 3 + \frac{5}{6} - 3 \ln S \right] \right\} \mathbf{n}
+ \left\{ C_1^* + \frac{m}{4\pi} KT \left[\ln \epsilon + \frac{5}{6} - \ln S \right] \right\} \mathbf{b} + \mathbf{E}_1 - (\mathbf{E}_1 \cdot \mathbf{t})\mathbf{t}$$
(39)

$$C_1^* = \pi \int_0^\infty \xi v^{(0)}(\xi, t) H s_{12}^{(2)}(\xi, t) d\xi$$
(40)

$$C_2^* = \pi \lim_{\overline{r} \to \infty} \left(\int_0^{\overline{r}} \xi v^{(0)}(\xi, t) H s_{11}^{(2)}(\xi, t) d\xi - \frac{1}{4} \frac{K^{(1)}(s, t)}{\pi^2} \ln \overline{r} \right)$$
(41)

$$Hs_{12}^{(2)} = 2\frac{\xi}{v^{(0)}(\xi,t)} \frac{\partial w^{(0)}(\xi,t)}{\partial \xi} \left(\dot{\mathbf{t}}^{(0)}(s,t) \cdot \mathbf{b}^{(0)}(s,t) \right) - 2\xi \frac{w^{(0)}(\xi,t)}{\sigma^{(0)}(s,t)} \frac{\partial K^{(0)}(s,t)}{\partial s}$$
(42)

$$Hs_{11}^{(2)} = 2\xi K^{(0)}(s,t) \frac{\partial v_c^{(1)}(\xi,t)}{\partial \xi} + v^{(0)}(\xi,t)K^{(1)}(s,t) + 2\frac{\xi}{v^{(0)}(\xi,t)} \frac{\partial w^{(0)}(\xi,t)}{\partial \xi} \left(\dot{\mathbf{t}}^{(0)}(s,t) \cdot \mathbf{n}^{(0)}(s,t)\right)$$

$$+6K^{(0)}(s,t)v_c^{(1)}(\xi,t) + 2\xi \frac{\partial v^{(0)}(\xi,t)}{\partial \xi} K^{(1)}(s,t) + 2\xi w^{(0)}(\xi,t)K^{(0)}(s,t)T^{(0)}(s,t)$$

$$+2\frac{\xi K^{(0)}(s,t)v_c^{(1)}(\xi,t)}{v^{(0)}(\xi,t)} \frac{\partial v^{(0)}(\xi,t)}{\partial \xi} + 2\frac{\xi K^{(0)}(s,t)w_c^{(1)}(\xi,t)}{v^{(0)}(\xi,t)} \frac{\partial w^{(0)}(\xi,t)}{\partial \xi}$$

$$+2\frac{\xi K^{(1)}(s,t)w^{(0)}(\xi,t)}{v^{(0)}(\xi,t)} \frac{\partial w^{(0)}(\xi,t)}{\partial \xi} + 2\frac{\xi K^{(0)}(s,t)w^{(0)}(\xi,t)}{v^{(0)}(\xi,t)} \frac{\partial w_c^{(1)}(\xi,t)}{\partial \xi}$$

$$(43)$$

This equation (39) is the first order equation of motion of the central line. Fukumoto and Miyazaki [4] (page 373) had written this equation without $K^{(1)}$, \mathbf{E}_1 and terms with the axial flux m.

V. CONCLUSION

A closed and complete system of equations (36,38,39) for the first order axisymmetric part $v_c^{(1)}$, $w_c^{(1)}$ of the velocity field and for the first order central line: $\mathbf{X}^{(1)}$ of a slender non circular vortex ring has been given. It would be interesting to find a simple case where a solution to these equations can be found and to compare these equations with those of a circular vortex ring [5].

VI. APPENDIX

In this appendix, terms that appears in formulas of section 2 are given.

$$\begin{split} m &= \pi \int_{0}^{\infty} \omega_{2} \overline{r}^{2} d\overline{r} = 2\pi \int_{0}^{\infty} w^{(0)} \overline{r} d\overline{r} \\ \mathbf{I}_{1} &= \frac{m}{\pi} \mathbf{t} \\ \mathbf{I}_{2} &= \frac{1}{2\pi} K m \cos \varphi \mathbf{t} \\ \mathbf{I}_{3} &= m \left[\left(\frac{1}{8\pi} K^{2} - \frac{1}{4\pi} T^{2} \right) \mathbf{t} - \frac{1}{4\pi} \left(K T \sin \varphi + 3 K_{s} \cos \varphi \right) \mathbf{e}_{r} - \frac{1}{4\pi} \left(K T \cos \varphi - 3 K_{s} \sin \varphi \right) \mathbf{e}_{\theta} \right] \\ \mathbf{I}_{4} &= \frac{m}{4\pi} \left\{ \left(\left[-\frac{5}{6} + \ln S \right] K T \sin \varphi + \left[-3 - \frac{5}{6} + 3 \ln S \right] K_{s} \cos \varphi \right) \mathbf{e}_{r} \right. \\ &\quad + \left(\left[-\frac{5}{6} + \ln S \right] K T \cos \varphi + \left[4 - \frac{1}{6} - 3 \ln S \right] K_{s} \sin \varphi \right) \mathbf{e}_{\theta} \\ &\quad + \left(\left(\left[-\frac{1}{2} \ln(2) + \frac{5}{16} - \frac{8}{5^{2}} + \frac{1}{4} \cos 2\varphi \right] K^{2} + \left[\ln(2) - \frac{3}{2} \right] T^{2} \right) \mathbf{t} \right\} \\ \mathbf{E}_{1}(a) &= \frac{m}{4\pi} \begin{cases} S/2 \\ \int_{-S/2}^{K(a+\overline{a})} \mathbf{b}(a+\overline{a}) \times (\mathbf{X}(a+\overline{a}) - \mathbf{X}(a)) + 2T(a+\overline{a}) \\ \left| \mathbf{X}(a+\overline{a}) - \mathbf{X}(a) \right|^{3} \right. \\ &\quad + 3 \left. \frac{\left[\mathbf{n}(a+\overline{a}) \cdot (\mathbf{X}(a+\overline{a}) - \mathbf{X}(a)) \right] \left(\mathbf{b}(a+\overline{a}) \times (\mathbf{X}(a+\overline{a}) - \mathbf{X}(a)) \right)}{\left| \mathbf{X}(a+\overline{a}) - \mathbf{X}(a) \right|^{3}} \\ &\quad - 3 \left. \frac{\left[\mathbf{b}(a+\overline{a}) \cdot (\mathbf{X}(a+\overline{a}) - \mathbf{X}(a)) \right] \left(\mathbf{n}(a+\overline{a}) \times (\mathbf{X}(a+\overline{a}) - \mathbf{X}(a)) \right)}{\left| \mathbf{X}(a+\overline{a}) - \mathbf{X}(a) \right|^{3}} \end{cases} \end{split}$$

$$+ \left(-2\frac{1}{|\overline{a}|^3} + \frac{K(a)^2}{4|\overline{a}|} - \frac{T(a)^2}{2|\overline{a}|}\right) \mathbf{t}(a) - \frac{K(a)T(a)}{2|\overline{a}|} \mathbf{b}(a) - \frac{3}{2} \frac{K_a(a)}{|\overline{a}|} \mathbf{n}(a) d\overline{a}$$

$$\mathbf{I}_5 = -\frac{1}{4\pi} \left[(K_s \sin \varphi - KT \cos \varphi) \mathbf{t} + \frac{3}{4} K^2 \sin(2\varphi) \mathbf{e}_r + \frac{3}{4} K^2 \cos(2\varphi) \mathbf{e}_\theta \right]$$

$$\mathbf{I}_6 = -\frac{1}{4\pi} \left[(K_s \sin \varphi - KT \cos \varphi) \left[1 - \ln S \right] \mathbf{t} + \left[1 - \frac{3}{4} \ln S \right] K^2 \sin(2\varphi) \mathbf{e}_r \right]$$

$$+ \left[\frac{4}{S^2} - \frac{K^2}{2^4} + \left(\frac{5}{8} - \frac{3}{4} \ln S \right) K^2 \cos(2\varphi) \right] \mathbf{e}_\theta$$

$$\mathbf{E}_2(\varphi, a) = \frac{1}{4\pi} \left(\mathbf{B}(\varphi, a) - 3\mathbf{C}(\varphi, a) \right)$$

with:

$$\mathbf{A}(a) = \frac{1}{4\pi} \int_{-S/2}^{+S/2} \left[\frac{\mathbf{t}(a+\overline{a}) \times (\mathbf{X}(a) - \mathbf{X}(a+\overline{a}))}{|\mathbf{X}(a) - \mathbf{X}(a+\overline{a})|^3} - \frac{K(a)\mathbf{b}(a)}{2|\overline{a}|} \right] d\overline{a}$$

$$\mathbf{B}(a) = \mathbf{e}_r(\varphi, a) \times \int_{-S/2}^{+S/2} \left[-\frac{\mathbf{t}(a+a')}{|\mathbf{X}(a) - \mathbf{X}(a+a')|^3} - f_b(a, a') \right] da'$$

$$\mathbf{C}(\varphi, a) = \int_{-S/2}^{+S/2} \left[\frac{\mathbf{e}_r(\varphi, a) \cdot (\mathbf{X}(a+a') - \mathbf{X}(a))}{|\mathbf{X}(a) - \mathbf{X}(a+a')|^5} \left[\mathbf{t}(a+a') \times (\mathbf{X}(a+a') - \mathbf{X}(a)) \right] - f_c(a, a') \right] da'$$

$$f_b(a, a') = -\frac{1}{|a'|^3} \left[\mathbf{t}(a) + K(a)\mathbf{n}(a)a' + \frac{a'^2}{2} \left[K_a(a)\mathbf{n}(a) + K(a)T(a)\mathbf{b}(a) - \frac{3}{4}K^2(a)\mathbf{t}(a) \right] \right]$$

$$f_c(a, a') = -\frac{K^2(a)\mathbf{b}(a)\cos(\varphi)}{4|a'|}$$

where S is the length of the vortex ring.

- [1] Bender C.M. and Orszag S.A. (1978) Advanced mathematical methods for scientists and engineers, McGraw-Hill, New York, 341-349
- [2] Callegari, A.J., Ting, L. (1978) Motion of a curved vortex filament with decaying vortical core and axial velocity, SIAM J. Appl. Math.35 (1), 148-175
- [3] François, C. (1981) Les méthodes de perturbation en mécanique. ENSTA. Paris, 98-104
- [4] Fukumoto, Y., Miyazaki, T. (1991) Three dimensional distortions of a vortex filament with axial velocity, J. Fluid Mech. 222, 369-416
- [5] Fukumoto, Y., Moffatt, H.K. (1997) Motion of a thin vortex ring in a viscous fluid : higher-order asymptotics , IUTAM Symposium on dynamics of slender vortices ,RWTH Aachen
- [6] Margerit, D. Mouvement et Dynamique des Filaments et des Anneaux Tourbillons de Faible Epaisseur (Dynamics and Motion of Slender Vortex Filaments and Rings) PhD Thesis INPL Nancy, France (November 1997)